

## Making-of: increasing the speed of Munich's U-Bahn stations renewal with construction robotics

MA Project: 8 SWS/ 12 ECTS, Wed. 14:00 – 18:30

Hybrid course (online + in-person)

Chair of Building Realisation and Robotics in collaboration with:

- Munich City Utilities & Transportation Corporation (SWM)
- & the Chair of Construction Management (Prof. Nübel)

# The Problem



Rights: Dorian Zapp, Münchner Verkehrsgesellschaft

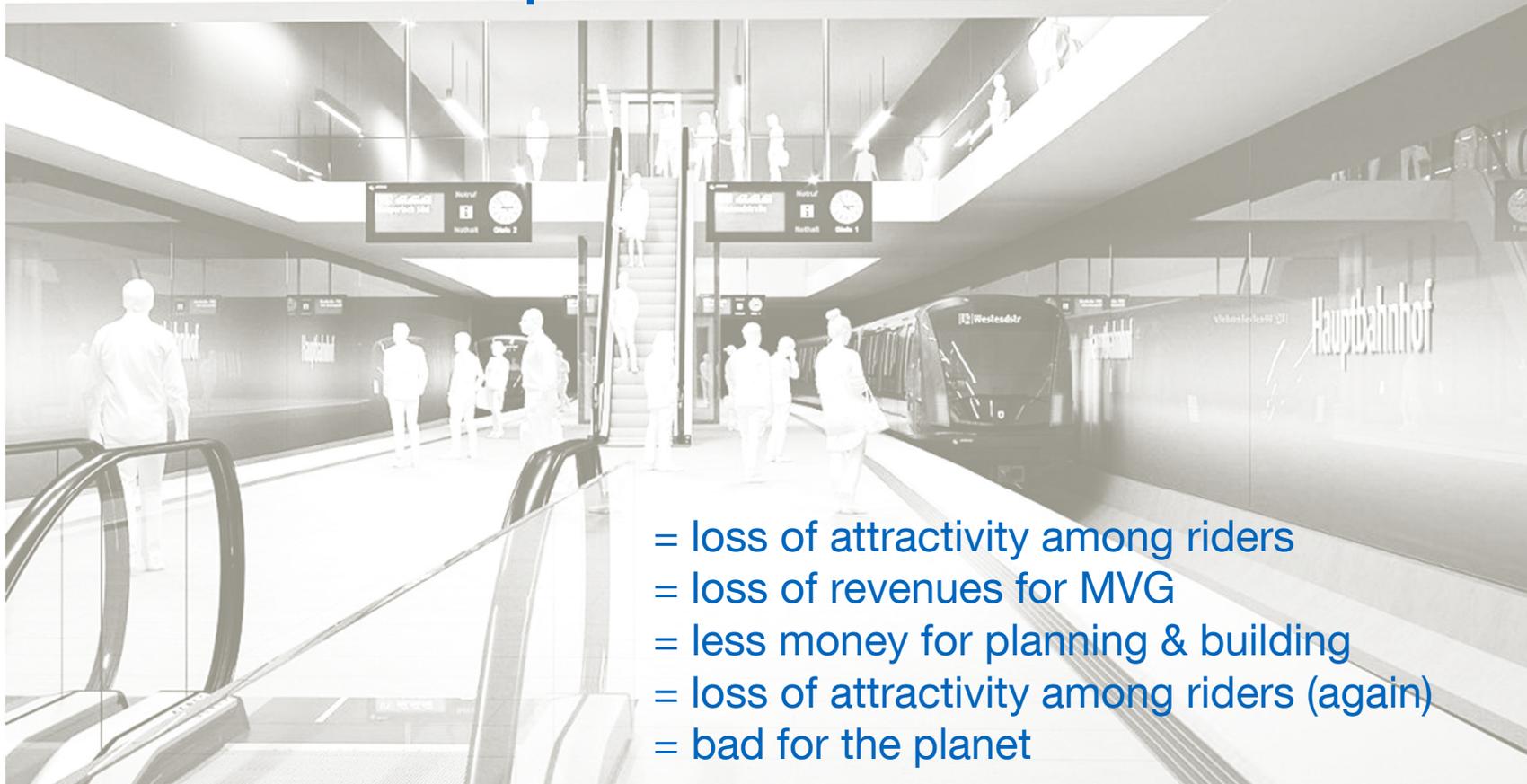
# The Goal: Exciting infrastructure protects the planet



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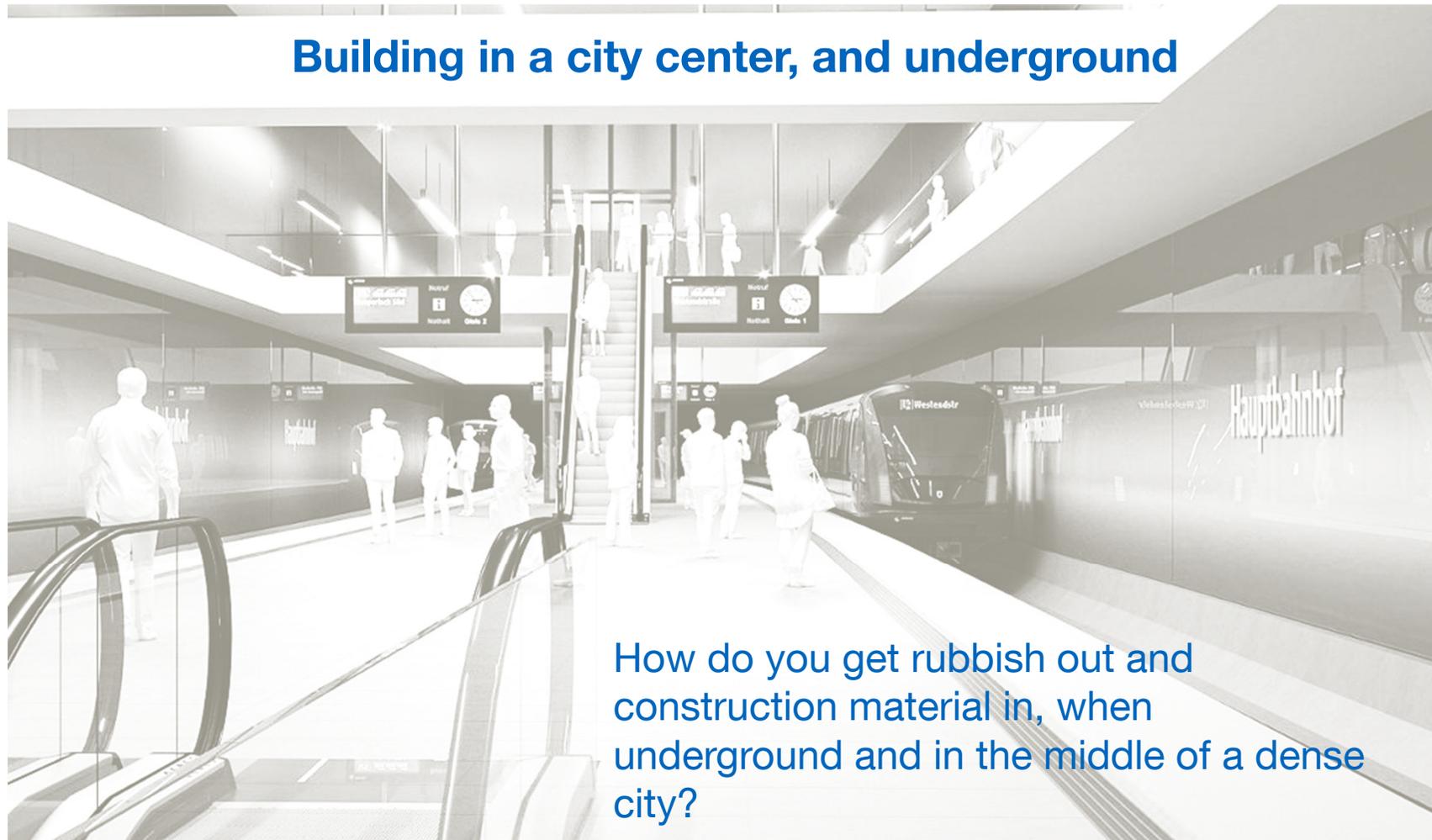
# What's so difficult?

**Service interruptions due to construction result in pain for customers**



# What's so difficult?

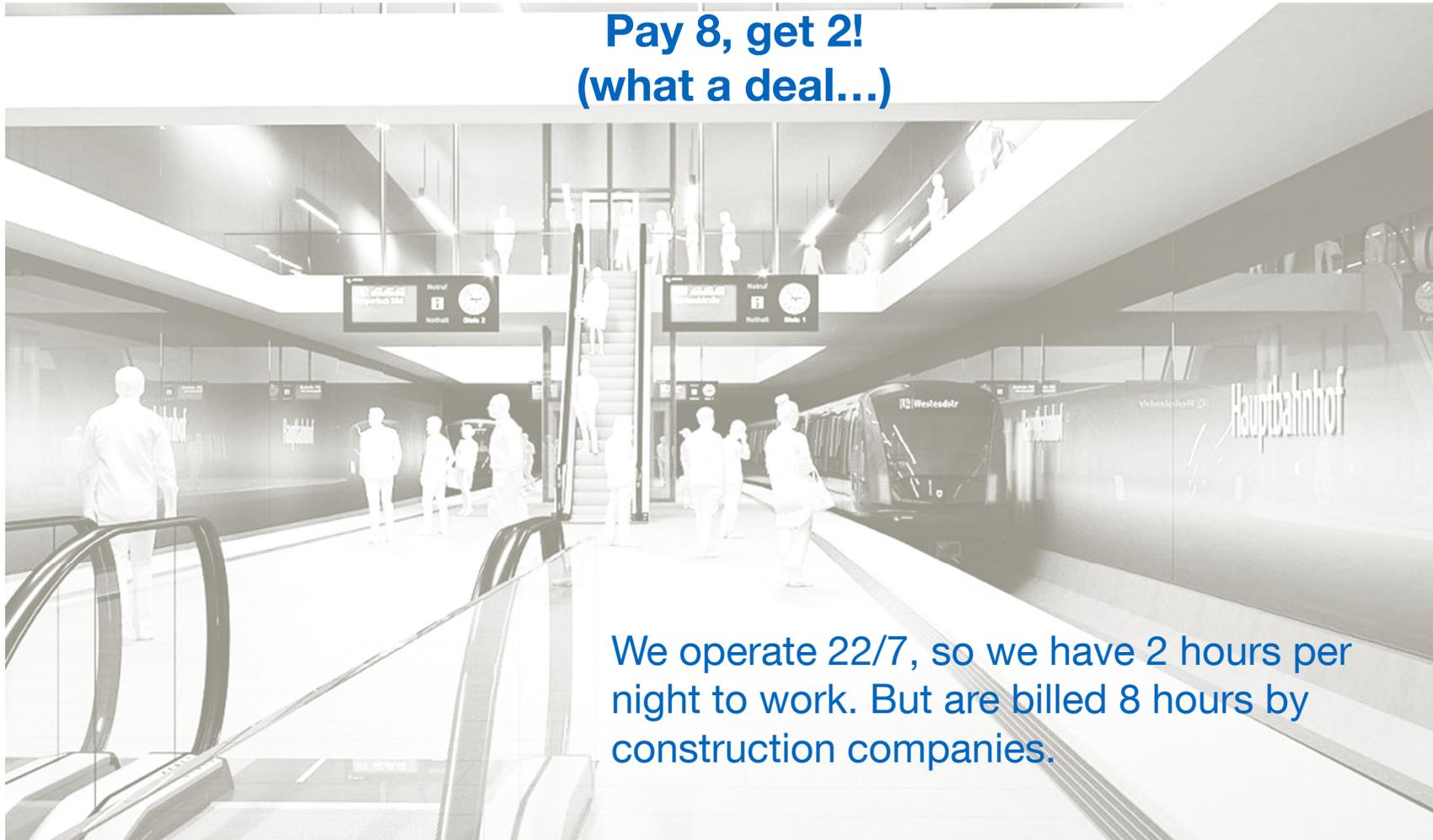
## Building in a city center, and underground



How do you get rubbish out and construction material in, when underground and in the middle of a dense city?

## What's so difficult?

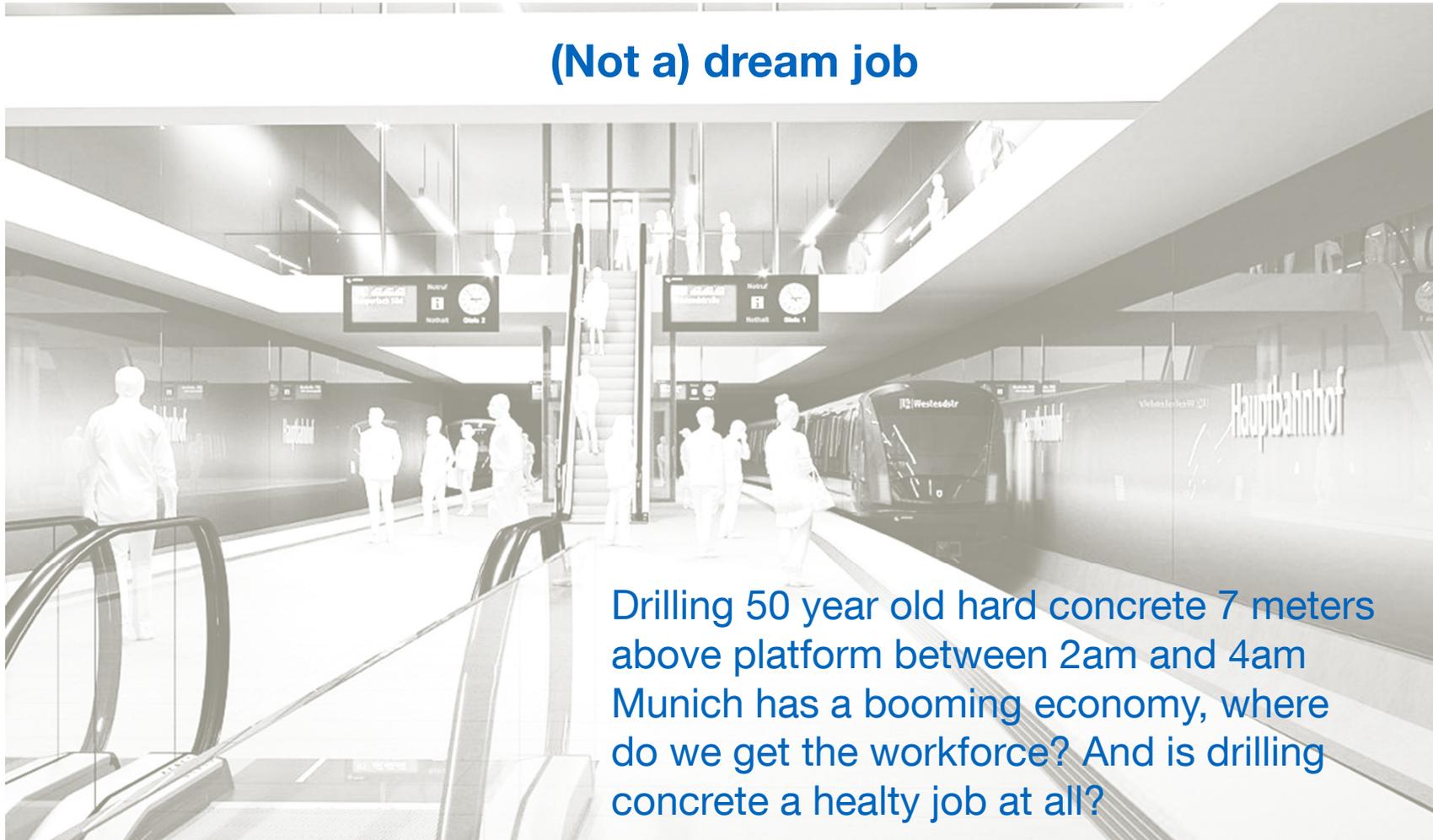
Pay 8, get 2!  
(what a deal...)



We operate 22/7, so we have 2 hours per night to work. But are billed 8 hours by construction companies.

# What's so difficult?

(Not a) dream job



Drilling 50 year old hard concrete 7 meters above platform between 2am and 4am  
Munich has a booming economy, where do we get the workforce? And is drilling concrete a healthy job at all?

## Help us!

We want to make the renderings reality, help us find solutions to bypass the problems that stands between renderings and reality.

We believe construction automation is one key element to make it happen.

Let's develop some construction robots together.



Façade painting robot developed by TUM + CIC Hong Kong



HEPHAESTUS cable robot for façade installation

# Robotized subway construction as a solution

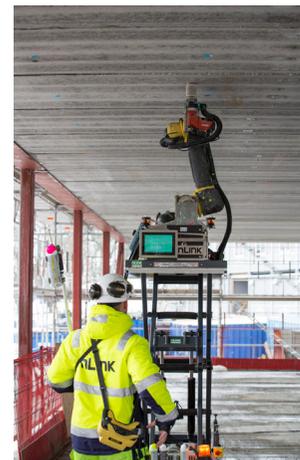
- Get to know the realities of the construction process and develop construction robot concepts on three focus topics (see next slide) to solve the issues.
- The Chair and the Munich City Utilities & Transportation Corporation give you input and guidance.



Shimizu concrete leveling robot



Taisei façade painting robot



nLink drilling robot



Transportation & logistics of Sekisui Heim

## Focus on 3 key tasks and get wild!

- Drilling concrete: is dangerous, dull and unhealthy, while requiring precise execution (do not harm the reinforcement bars) and an individual documentation is required: depth, torque, touched reinforcement bar, ... Drilling makes construction sites dirty, requiring extensive and expensive work safety and cleaning measures.
- Site progress monitoring and management: at any moment, you need to know if you are on schedule, and if there is any potential risk for train traffic. You also need to ensure how construction was made. We need to build more and more at the same time at night, but can't get our hands on enough site managers.
- Site logistics: this is a major bottle-neck. Getting construction material in and out, in the heart of the city, up to 10 stories underground. Imagine how fast and how much cheaper we could build, with an Amazon-like construction logistics.

# Course timeline

- Week 1 (Nov 2-8): introduction of topic and problems/tasks (lead: SWM); type: recorded lecture
- Week 2 (Nov 9-15): introduction to potential solutions (lead: br2); type: recorded lecture
- Week 3-6 (Nov 16 - Dec 13): desk critique (in elective courses: individual program by lecturers)
- Week 7 (Dec 14-20): intermediate presentations 1
- Week 8-10 (Dec 21 - Jan 10): desk critique (in elective courses: individual program by lecturers)
- Week 11 (Jan 11-17): intermediate presentations 2
- Week 12-14 (Jan 18 - Feb 7): desk critique (in elective courses: individual program by lecturers)
- Week 15 (Feb 8 - Feb 14): final presentations

## Linked (non-mandatory) courses

- Robot Oriented Design (ROD) – **Drilling concrete**  
 2SWS/ 3ECTS, Thurs. 13:15– 14:45, Mode: Online
- Design of Robots in Architectural Context (DoRiAC) – **Site progress monitoring and management**  
 2SWS/ 3ECTS, Mond. 08:00– 09:30, Mode: Online
- Automation & Robotics in Construction (ARC) – **Site logistics**  
 4SWS/ 6ECTS, Thurs. 9:45 – 12:45, Mode: Online
- Selected courses of the Chair of **Construction Management**, TUM  
 Department of Civil, Geo and Environmental Engineering

# Summary

<b>Title:</b>	Making-of: increasing the speed of Munich's U-Bahn stations renewal with construction robotics
<b>Chair:</b>	Chair of Building Realization and Robotics, in collaboration with: <ul style="list-style-type: none"> <li>• SWM: Stéphane Schneider, head of subway construction</li> <li>• Guest critics from start-ups and industry</li> </ul>
<b>Language:</b>	English, English support (i.e. lecture/learning materials in English, group work/individual reviews in English)
<b>Study level:</b>	Master
<b>Kick off:</b>	See course timeline
<b>Meetings:</b>	Wed. 13:15 – 17:45; Room: <u>virtual per Moodle</u>
<b>Interm. Reviews:</b>	See course timeline
<b>Final Presentation:</b>	See course timeline
<b>ECTS:</b>	12 ECTS (+3 ECTS)